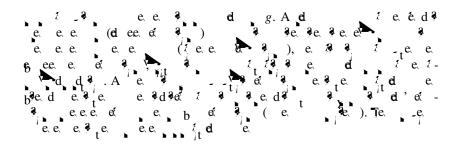
e. 3 d i de i se sis (d, 2,), e, e, e, e, e, e,

2.1 Vertex Features



2. Ita P. d. b., Ita, a

3 OUTCOMES ON NETWORKS

Proposition 1 If < 1, + = 0, $W_{ij} = (N-1)^{-1}$ if i = j and $W_{ii} = 0$, (, ,) is not point-identified.

e e d M

 $y_i = + \mathbb{E}(y_i \ W) + x_i + \mathbb{E}(x_i \ W) + i, \mathbb{E}(x_i \ W) + i,$

 x_i . A e. d t b M3 (1993) 3 d t e. e. e. e. d t 13 e. e. 1 d e. d ď W (. . 535). Te e, e, , e e e ee e, e, e, ed_be_d de de 🦸 d e. $\mathbb{E}(x_j | w)) = 0, e \quad 3 \text{ d}$ 31 e, e, d **d** (2) le de de l, e a .I e.e. ₃e.¹ $(x) = {}^{2}I, e$ $^{2}(\mathbf{I} - W)^{-2}$

The distribution of the control of

Proposition 2 If < 1, $W_{ij} = (N-1)^{-1}$ if i = j, $W_{ii} = 0$, and $\mathbb{V}(\mathbf{x}) = {}^{2}\mathbf{I}$ then (,,,) is point-identified.

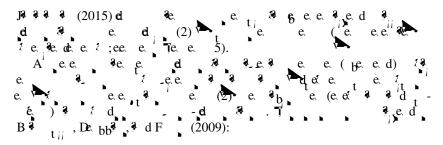
, e, 1 3 3 et e, ³_b e√ I e, e, be& le ê e d³ d e_{λ} a d, _t e e %e d. (O ℓ_t e, de le e l _e, e, d. 3 11 -1. Te b t e 31 bt deē e' e 133ee þ. d ¹² C **3 3 e** e. a e ae. d e. e. t e. e, _e, e, e. 1 e. e, e i e i e d b P 3 3 d 1 ,e. '**d** e e $\frac{e}{b}$ $\frac{d}{d} = 0.50$.

Proposition 3 If < 1, $W_{ij} = (N-1)^{-1}$ if i = j, $W_{ii} = 0$, and $\mathbb{V}(\mathbf{x}) = {}^{2}\mathbf{I}$ then

$$\frac{\mathbb{C}(y_i, y_j \mathbf{x})}{\mathbb{V}(y_i \mathbf{x})} > \frac{4 - 3N}{4N^2 - 11N + 8}.$$

 $\mathbf{y}_{l \ N_{l} \ 1} = W_{l \ N_{l} \ N_{l} \ l \ N_{l} \ 1} + {}_{l} \mathbf{1}_{N_{l} \ 1} + {}_{l \ N_{l} \ 1},$

e.e. N_l e. g. d. d. d. t - l. $W_{ij,l} = (N_l - 1)^{-1}$ i = j d. $W_{ii,l} = 0$, d. d. t - e. t l. e. d. t e. t e



Proposition 4 (B ? , D. bb² , d F , 2009) If + = 0 and I, W, W^2 are linearly independent, (, , ,) is point-identified.

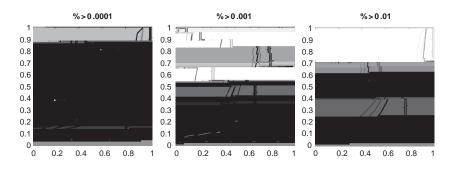
I
$$W_{ij} = (N-1)^{-1}$$
 $i = j$ 3 d $W_{ii} = 0$, $W^2 = (N-1)^{-1}$ **I** +



F_te 1 De é dC é N

e.e. Te. W^2 , W^2

JT e d é d e (e E e d b B d d H d t d d K (2014), d K d e t e t b d 't - - d d 3 ...) T e d e d (M O) 1 t t t d , 2 d 2 d ₹ 3 3e. . Te. 3 e. b3 $\mathbf{d}_{\mathbf{k}}$ xt e lagged ! Te e, y_{it} e b te. t e d b Ma e 3 (2013) e, = I + W (1 3e $t e^{t} e^{t} = 0$ = 0 (? M? e. ?, 2013), = 0 (? M? e. ?, 2013), = 0 (? M? e. ?, 2013), = 0 (? M? e. ?, 2013),e - 3 d d d 3 - e d e 1 .24 a d e_{c} e_{c} $= \mathbf{I} + \mathbf{W} \mathbf{e}$



The end of the end of

$$\mathbf{v}_{t}(W_{t+1}, t) \frac{1}{T} \sum_{t} \|\mathbf{y}_{t} - \mathbf{w}_{t} - \mathbf{w}_{t} - \mathbf{x}_{t} - \mathbf{w}_{t}\|_{2}^{2} + \sum_{i=j} p_{T}(W_{ij}),$$
(6)

3.2 Nonlinearities and Multiple Equilibria

 $\mathbf{d}_{\mathbf{k}}$, $\mathbf{b}_{\mathbf{k}}$ \mathbf{e} , \mathbf{e} ,

d is de tild ete tiee.

4 NETWORK FORMATION

A ea ${}^{3}b$ e, e 1 e 1 e e e d 3 e e e d 3 e' e'3 e e e d leed e

4.1 Statistical Models

e (G), edbe 3 d d e d N e e e $\frac{1}{t}$ $\frac{1}{t$ 3. G,3 d → 3 13 (G, (G)). I e d de e - 3 3 e e e e N d . (I i e e t de é de -(¹te. .) A e ? ? ? e & g ee 3 e e 3 3 3 B d e d but not necessarily more than

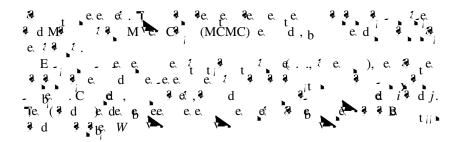
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tide ed ? E GM. Te. (2014) 3 d Me (2015) 3 d (2011). I - 3 3e (d e d3 e MCMC. e de e de dd _ e, 3 . e). I e e $O(n^2 - n)$ (Te. e. E GM Oadfaalde alle eeb de degeneracy near degeneracy, e, ee, e e de dibe **e**, **e**, e, e' e'

de d , b b b, e be -

geedd deéde.) A. tie 6 e, e, e d b e, de, e e de (C 3 d 3e. €. e de e e de $d\,\mathbf{g}$ i,j, j,k, i d k,ie d t e 3 e i, j i, j, k). De d e. e. 🔰 1 de b

d GM -Me (2015) e. Addlet 🥞 B³e. e, e, 🕴 C į **M**e (2015)e ee ! e , 3 d B3 d (2013) t e . (Te Addlet 🏞 de 🫊



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, 2013), d G e d d ee e e t e, e d e Addle 7 , 2011 3 d M , e , 2015). A e e de d de d Bre ee, C d d de

A PROOFS

A.1 Proof of Proposition 2

I
$$\mathbb{V}(\mathbf{x}) = {}^{2}\mathbf{I}, \text{ e. } \mathbb{V}(\mathbf{y} \mathbf{x}) = {}^{2}(\mathbf{I} - W)^{-2}.$$
 Set $< 1 \text{? d } W$.

$$(\mathbf{I} - W)^{-1} = \mathbf{I} + W + {}^{2}W^{2} + \dots$$

I
$$a_{k}$$
 a_{k} $a_$

$$\mathbf{E} \quad S = \sum_{k=1}^{\infty} S_k = 1$$

e. e. *! * $\mathbb{V}(y x) = {}^{2}(I + S)^{2}$, e. * . 6 ee. ! * e.

O e e ? d, e t? d? ? e e p(b; -, N) . e ,? d $- \frac{-(N-2)}{(N-2)^2 + }$

e.
$$\mathbf{t} = \frac{\mathbf{c} \cdot \mathbf{d} \cdot \mathbf{d}_{i} \cdot \mathbf{r}}{\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{d}_{i} \cdot \mathbf{r}} \cdot \mathbf{r} \cdot \mathbf{c}$$
, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$, $\mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}$.

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